

# Minimum Cost Spanning Trees (MSTs)

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# Outline

- 1 Introduction
- 2 Kruskal's algorithm
- 3 Prim's algorithm
- 4 Sollin's algorithm



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# Cost & Minimum-Cost Spanning Tree

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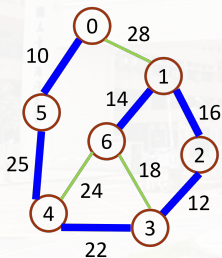
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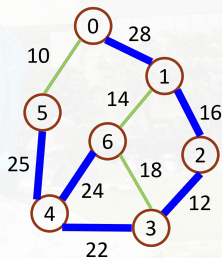


# Cost & Minimum-Cost Spanning Tree

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$$\text{cost} = 10 + 25 + 22 + 12 + 16 + 14 = 99.$$



$$\text{cost} = 28 + 16 + 12 + 22 + 24 + 25 = 127.$$



# Greedy Methods

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  - Kruskal's algorithm
  - Prim's algorithm
  - Sollin's algorithm
- ★ Further reading: Greedy Algorithms & Matroids [[link](#)]





# Greedy Method (1/2)

- Construct an optimal solution in stages.
- A feasible solution is one which works within the constraints specified by the problem.
- At each stage, we make a decision that is **the best decision at that time**.
- Typically, The selection of an item at each stage is based on either a **least cost** or a **highest profit** criterion.



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  - We must use only edges within the graph.
  - Exactly  $n - 1$  edges are used.
  - Never use edges that would produce a cycle.



## TBD

```
void transpose(term a[], term b[]) { // b is set to the transpose of a
    int n, i, j, currentb;
    n = a[0].value; // total number of elements
    b[0].row = a[0].col; // rows in b = columns in a
    b[0].col = a[0].row; // columns in b = rows in a
    b[0].value = n;
    if (n > 0) { // dealing with a nonzero matrix
        currentb = 1;
        for (i=0; i<a[0].col; i++) // transpose by the columns in a
            for (j=1; j<=n; j++) // find elements from the current column
                if (a[j].col == i) { // element is in current column, add it to b
                    b[currentb].row = a[j].col;
                    b[currentb].col = a[j].row;
                    b[currentb].value = a[j].value;
                    currentb++;
                }
    }
}
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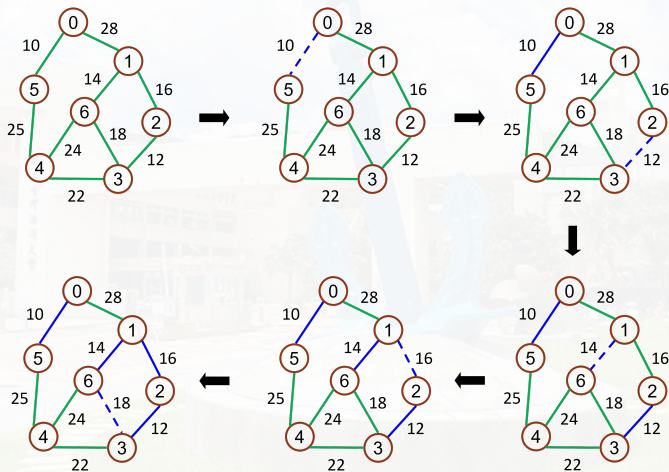


## Kruskal's Algorithm

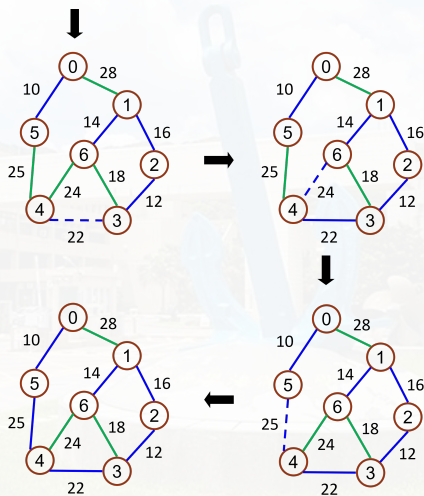
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  - **How to do this?**  $\Rightarrow$  **Union-Find Operations!**
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# Illustration of Kruskal's Algorithm



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# Union-Find Operations

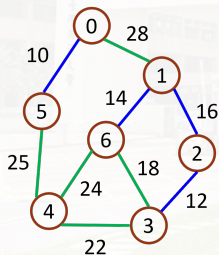
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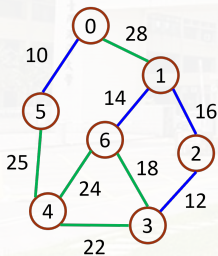


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- $\{0, 5\}$ ,  $\{1, 2, 3, 6\}$ ,  $\{4\}$ : the sets corresponding to existing subtrees.
- Vertex 3 and 6 are already in the same set  $\Rightarrow$  edge  $(3, 6)$  is rejected!



# The Pseudo-code of Kruskal's Algorithm

```
T = { };
while (T contains fewer than n-1 edges && E is not empty) {
    choose a least cost edge (v,w) from E;
    delete (v,w) from E;
    if ((v,w) does not create a cycle in T)
        add (v,w) to T
    else
        discard (v,w);
}
if (T contains fewer than n-1 edges)
    printf("No spanning tree\n");
```

- How could “No spanning tree” happen?
- e union-find takes  $O(e \log^* e)$  time (supplementary)



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- Another greedy MST algorithm.
- The main difference:
  - The set of selected edges forms a **tree at all times** in Prim's algorithm.
  - The set of selected edges in Kruskal's algorithm forms a *forest at each stage*.



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- Repeat this edge addition until  $T$  contains  $n - 1$  edges.



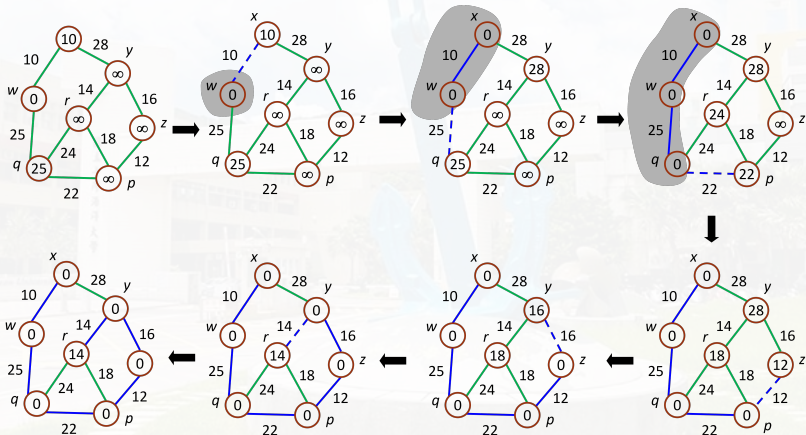
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Time complexity:  $O(n^2)$ .



# Illustration of Prim's Algorithm



## Prim's Algorithm (3/3)

```
T = {}; TV = {0};
while (T contains fewer than n-1 edges) {
    let (u,v) be a least cost edge such that u is in TV and
    v is not in TV;
    if (there is no such edge )
        break;
    add v to TV;
    add (u,v) to T;
}
if (T contains fewer than n-1 edges)
    printf("No spanning tree\n");
```

- Each vertex  $v \notin TV$  has a companion vertex "near(v)" such that  $\text{near}(v) \in TV$  and  $\text{cost}(\text{near}(v), v)$  is minimum over all such choices for near(v).
- Therefore, it takes  $O(n)$  time to choose an edge.
- We can implement Prim's algorithm in  $O(n^2)$  time.

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## Sollin's Algorithm (1/2)

- Sollin's algorithm selects several edges for inclusion in  $T$  at each stage.
- At the start of a stage, the selected edges, together with all the  $n$  vertices, form a spanning forest.
- During each stage, we select one edge for each tree in the forest.
  - This edge is a minimum cost edge that has exactly one vertex in the tree.



## Sollin's Algorithm (2/2)

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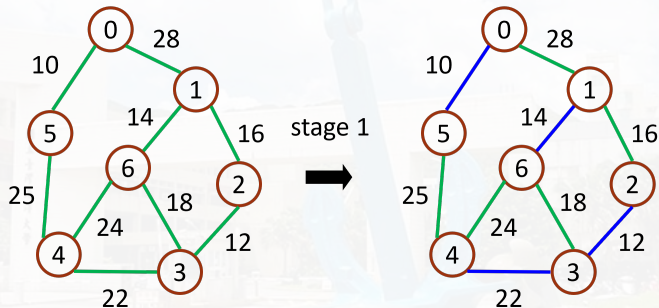
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- **Note:** two trees in the forest could select the same edge.
  - We need to **eliminate duplicate edges**.
- At the start of the first stage the set of selected edges is empty.
- The algorithm terminates when there is **only one tree at the end of a stage** or **no edges remain for selection**.

We can implement Sollin's algorithm in  $O(e \log v)$  time.

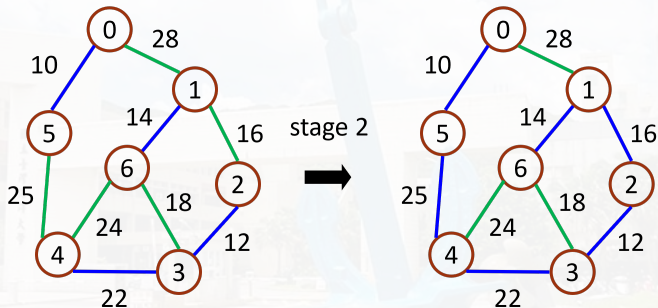


# Illustration of Sollin's Algorithm



- Stage 1:  $(0, 5)$ ,  $(1, 6)$ ,  $(2, 3)$ ,  $(3, 2)$ ,  $(4, 3)$ ,  $(5, 0)$ , and  $(6, 1)$  are selected, and then duplicates are removed.

# Illustration of Sollin's Algorithm



- Stage 2:  $(5, 4)$ ,  $(1, 2)$ , and  $(2, 1)$  are selected, and then duplicates are removed.



# Discussions

