Connected Components & Biconnected Components

Joseph Chuang-Chieh Lin (林莊傑)

Department of Computer Science & Engineering, National Taiwan Ocean University

Fall 2024



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Components & Biconnected Components

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Components & Biconnected Components

Outline



Connected Components

- Spanning Trees
- Articulation Points & Biconnected Graph
- Finding the articulation points



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Connectivity

Problem I

Determine if an (un)directed graph is connected.





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We can solve this problem by calling either dfs(v) or bfs(v) for an arbitrary vertex $v \in V(G)$, and then determining if there are any unvisited vertices.



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List all connected components of an (un)directed graph.



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Problem II

List all connected components of an (un)directed graph.

This can be done by making repeated calls to either dfs(v) or bfs(v) where v is an unvisited vertex.



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```
void connected(void) { // dfs(0) or bfs(0)
/* determine the connected components of a graph */
    int i;
    for (i=0; i<n; i++) {
        if (!visited[i]) {
            dfs(i);
            printf("\n");
        }
    }
}</pre>
```



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Analysis of connected

• If G is represented by its adjacency lists, then the total time taken by DFS is O(e).



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- Since the for loop takes O(n) time, the total time needed to generate all the connected components is O(n + e).
- If G is represented by an adjacency matrix, then the time needed to determine the connected components is $O(n^2)$.



Spanning Trees

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• When graph G is connected, a DFS or BFS implicitly partitions the edges in G into two sets:



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Spanning Trees

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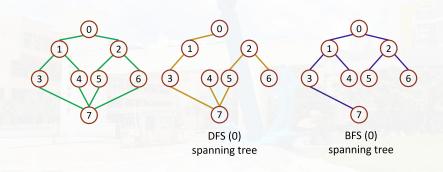
A tree T is said to be a *spanning tree* of a connected graph G if T is a subgraph of G and T contains all vertices of G.

- When graph G is connected, a DFS or BFS implicitly partitions the edges in G into two sets:
 - Tree edges: the set of edges used or traversed during the search.
 - Nontree edges: the set of remaining edges.

G1

Three spanning trees of G₁.

DFS Spanning Trees & BFS Spanning Trees





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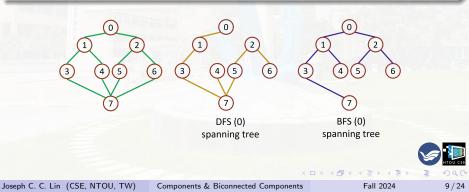
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Properties of (DFS or BFS) Spanning Trees

Property I

Suppose we add a nontree edge, (v, w), into any spanning tree, T. The result is a cycle that consists of the edge (v, w) and all the edges on the path from w to v in T.

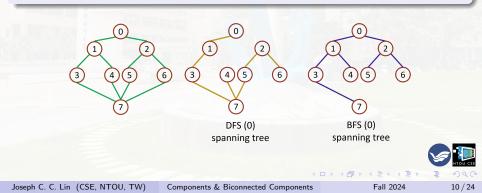


Properties of (DFS or BFS) Spanning Trees

Property II

A spanning tree is a minimal subgraph, G', of G such that V(G') = V(G) and G' is connected.

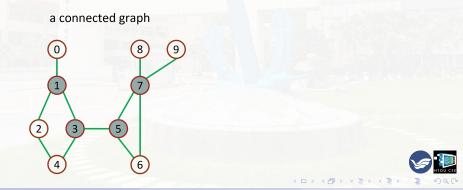
• A spanning tree has n-1 edges.



Articulation Points

Articulation Points

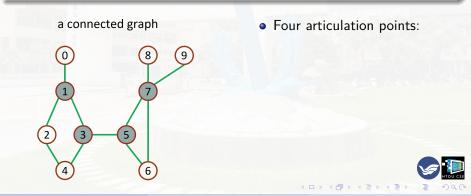
An **articulation point** is a vertex v of G such that the deletion of v, together with all edges incident on v, produces a graph, G', that has ≥ 2 connected components.



Articulation Points

Articulation Points

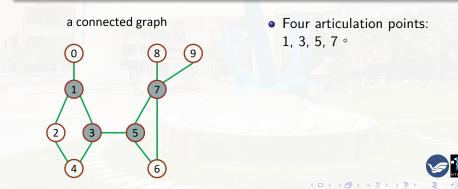
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Biconnected Graph

Biconnected Graph

A biconnected graph is a connected graph that has NO articulation points.

Biconnected Component

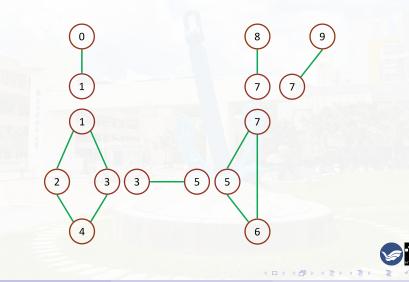
A biconnected component of a connected graph G is a maximal biconnected subgraph H of G.

• *H* is "maximal": no other subgraph that is both biconnected and properly contains *H*.

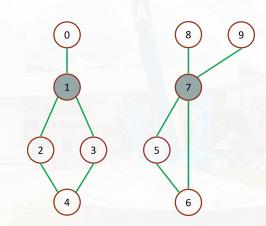


Biconnected Components (





Biconnected Components (NOT an Example)





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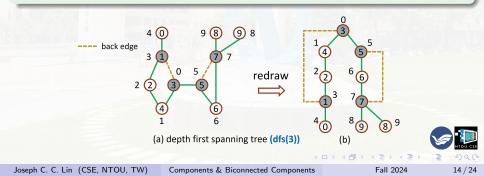
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Finding articulation points (1/3)

We can find biconnected components of a graph G using any depth-first spanning of G.

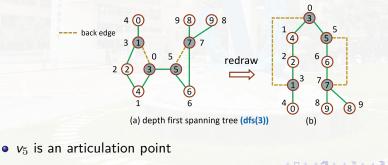
Back edges

- Tree edges: DFS
- Nontree edges: we call them back edges



Observations

- The root of a depth first spanning tree is an articulation point if and only if it has ≥ 2 children.
- Any other vertex u is an articulation point if and only if it has ≥ 1 child w such that we cannot reach an ancestor of u using that consists of only w, descendants of w, and a single back edge.

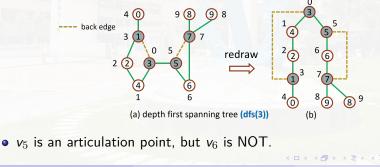




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Finding articulation points (2/3)

dfn(v)

The depth first numbers, or dfn, of the vertices give the sequence in which the vertices are visited during the depth first search.



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Finding articulation points (2/3)

dfn(v)

The depth first numbers, or dfn, of the vertices give the sequence in which the vertices are visited during the depth first search.

• If u is an ancestor of v in the depth first spanning tree, then dfn(u) < dfn(v).

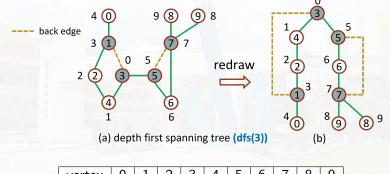
low(v)

The low(u) value of vertex u is the lowest depth first number that we can reach from u using a path of descendants followed by at most 1 back edge:

 $\mathsf{low}(u) = \min \left\{ \begin{array}{l} \mathsf{dfn}(u), \\ \min\{\mathsf{low}(w) \mid w \text{ is a child of } u\}, \\ \min\{\mathsf{dfn}(w) \mid (u, w) \text{ is a back edge}\} \end{array} \right.$

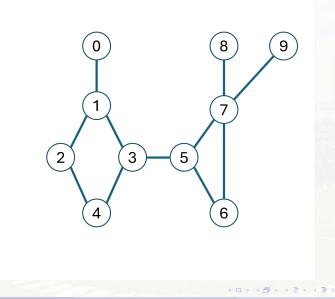


Example of Computing dfn and low values

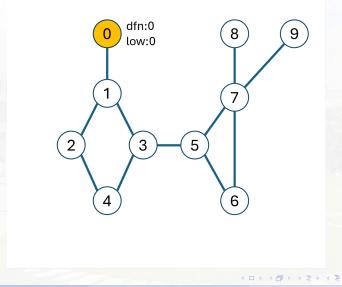


vertex	0	1	2	3	4	5	6	7	8	9
dfn	4	3	2	0	1	5	6	7	9	8
low	4	0	0	0	0	5	5	5	9	8

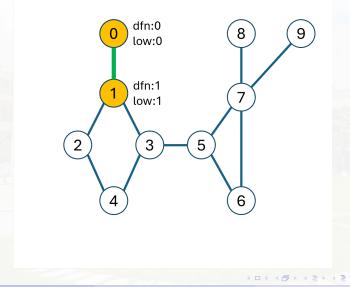
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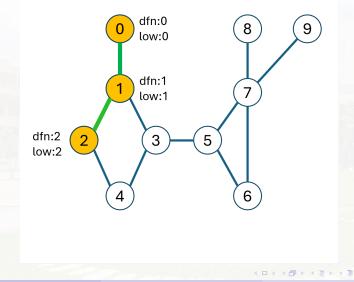


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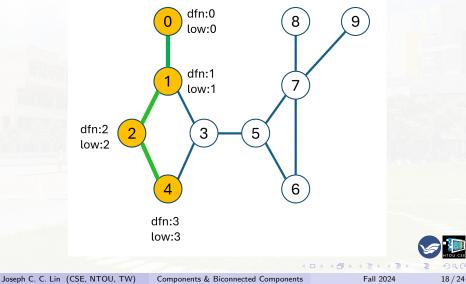


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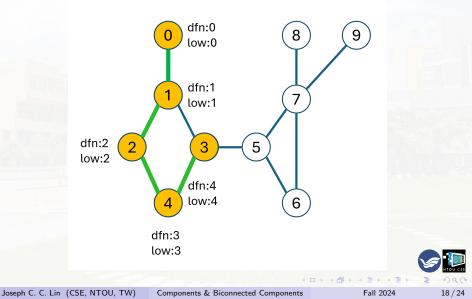
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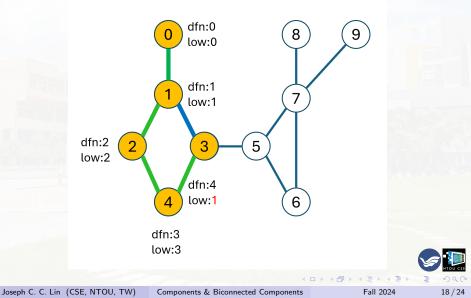


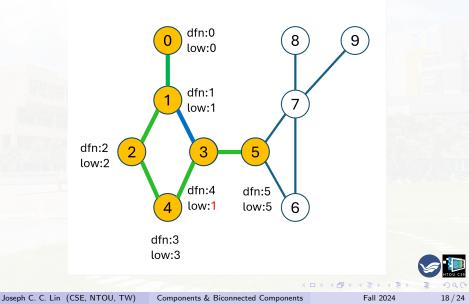
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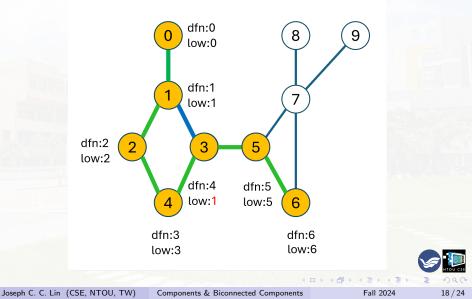


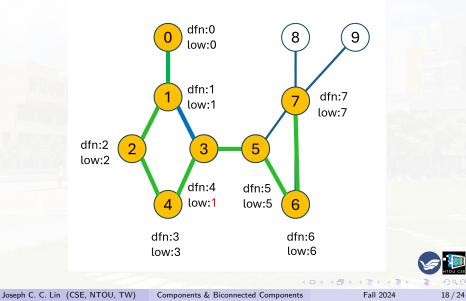
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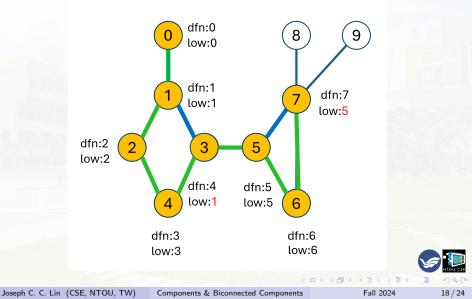


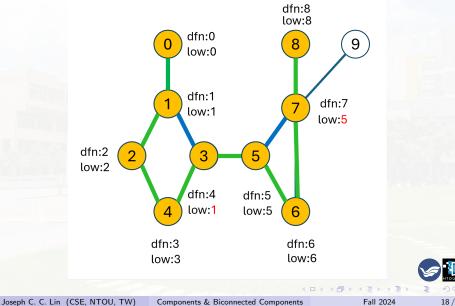




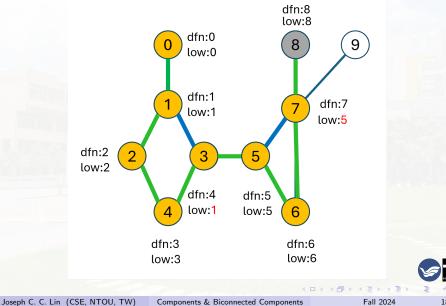


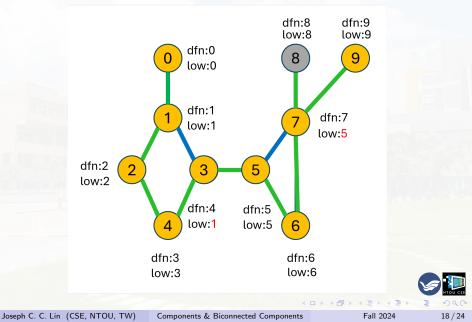


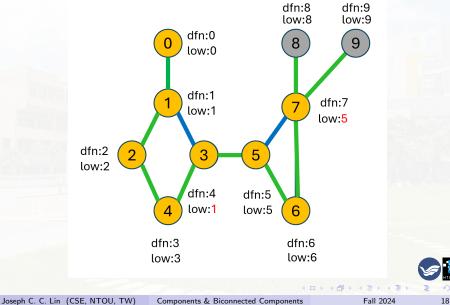


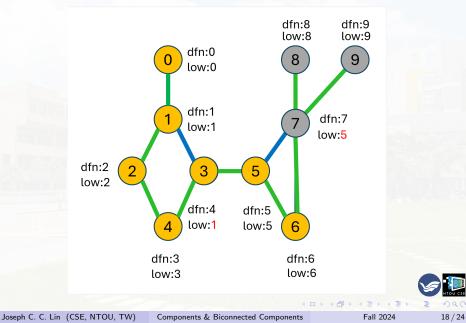


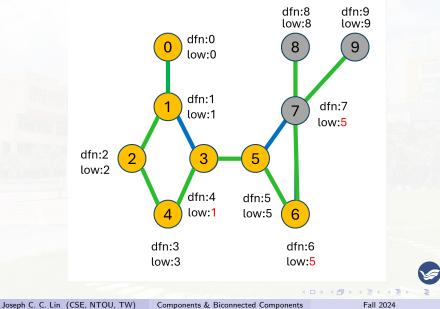
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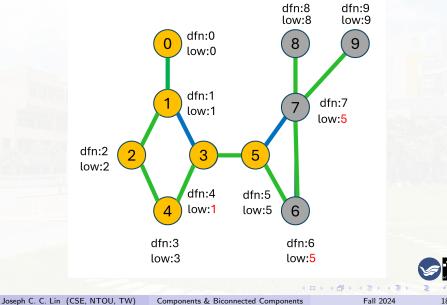


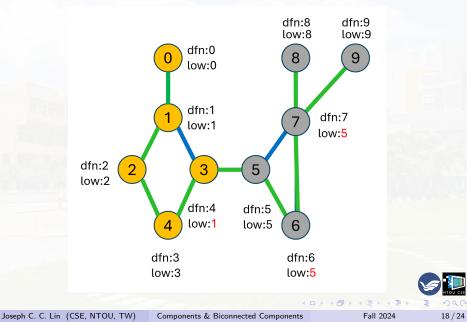


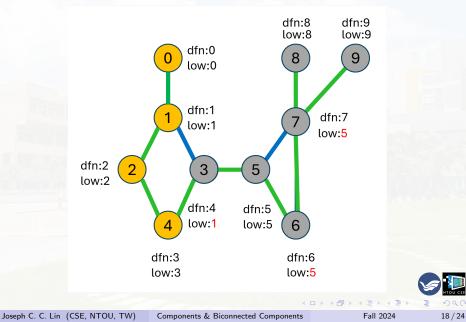


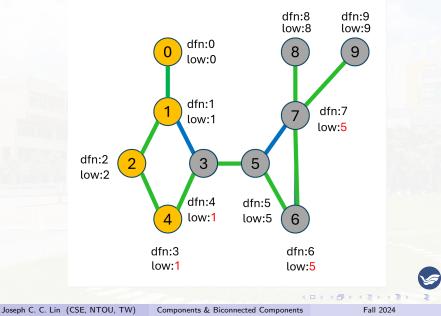


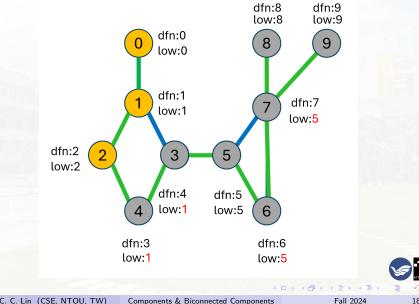








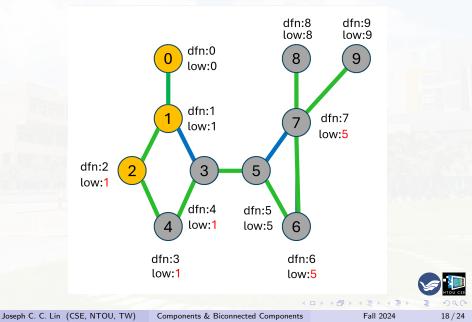


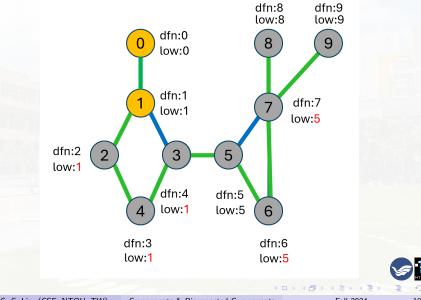


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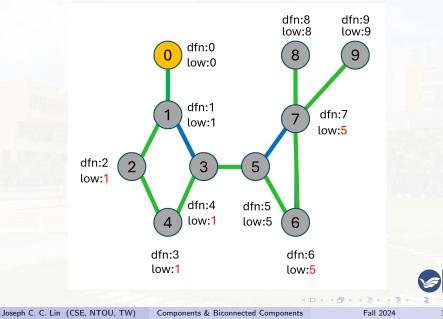


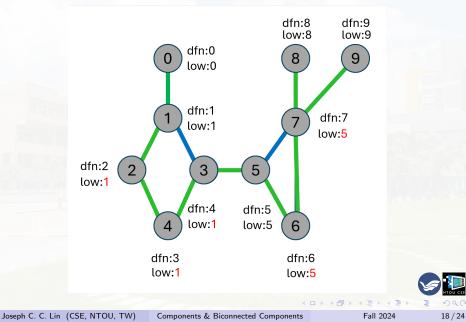
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The codes for computing dfn and low

```
Time complexity: O(e).
```

```
void dfn low(int u, int v) {
/* compute dfn and low while performing a dfs
search beginning at vertex u, v is the parent
of u (if any) */
    node_pointer ptr;
    int w;
    dfn[u] = low[u] = num++;
    for (ptr = graph[u]; ptr; ptr = ptr->link) {
        w = ptr ->vertex;
        if (dfn[w] < 0) {
        /*w is an unvisited vertex */
            dfn low(w, u);
            low[u] = MIN2(low[u], low[w]);
        } else if (w != v)
            low[u] = MIN2(low[u], dfn[w]);
    }
```

```
short int dfn [MAX_VERTICES];
short int low[MAX_VERTICES];
int num = 0;
```

```
void init(void) {
    int i;
    for(i = 0; i < n; i++) {
        visited[i] = FALSE;
        dfn[i] = low[i] = -1;
    }
    num = 0;
}</pre>
```

bootstrapping by

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 $dfn_low(x, -1)$



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Finding articulation points (3/3)

articulation points

u is an articulation point iff one of the following conditions are satisfied:

- *u* is the root of the spanning tree and has two or more children.
- *u* is not the root of the spanning tree and *u* has a child *w* such that low(*w*) ≥ dfn(*u*).



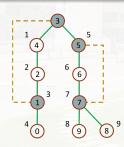
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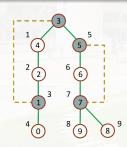
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dfn	4	3	2	0	1	5	6	7	9	8
low	4	0	0	0	0	5	5	5	9	8

• articulation points: 1, 3, 5, 7.



Algorithm for Finding Biconnected Components

If we have $low[w] \ge dfn(v)$ when $dfn_low(u, w)$ returns.



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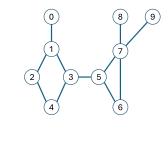
Code for Biconnected Components (O(n + e) time)

```
void bicon(int u, int v) { /* dfn[] = -1, num = 0, s is an empty stack initially*/
   nodePointer ptr:
   int w, x , y;
   dfn[u] = low[u] = num++;
   for (ptr = graph[u]; ptr; ptr = ptr->link) {
        w = ptr->vertex:
        if (v != w && dfn[w] < dfn[u]) {
            push(u,w): /* add edge (u,w) into stack s */
            if (dfn[w] < 0) { /* w is not visited yet */
                bicon(w, u);
                low[u] = MIN2(low[u], low[w]);
                if (low[w] >= dfn[u]) {
                    printf("New biconnected component:");
                    do { /* pop an edge from stack s */
                        pop(&x. &v);
                        printf("<%d,%d>".x, v);
                    } while (!((x == u) && (y == w)));
                    printf("\n");
                3
            } else if (w != v)
                low[u] = MIN2(low[u],dfn[w]);
       }
    3
}
```

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Illustration



stack



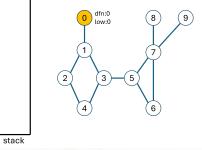
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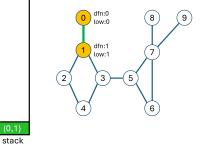
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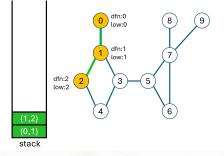
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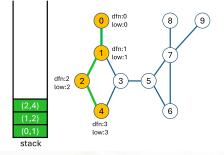
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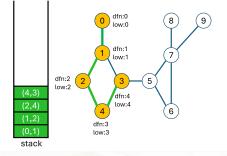
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Illustration





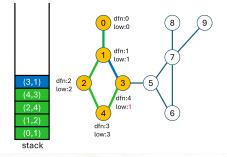
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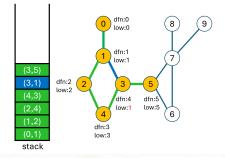
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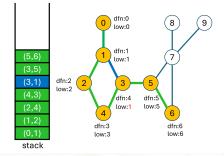
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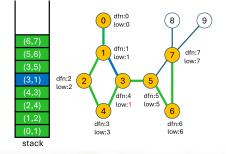
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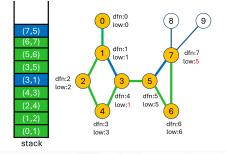
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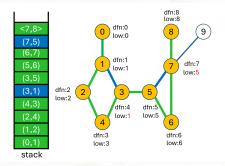
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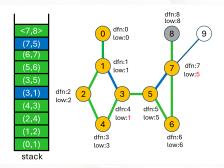
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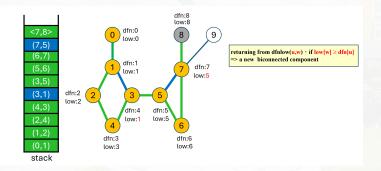
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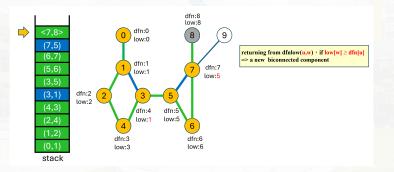
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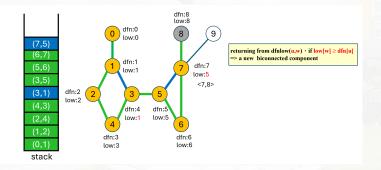
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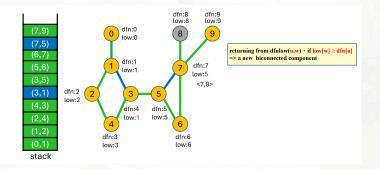
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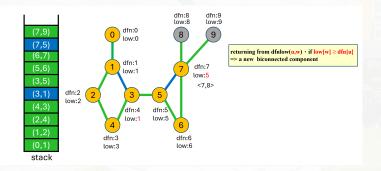
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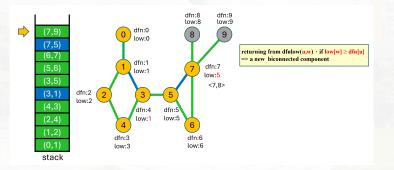
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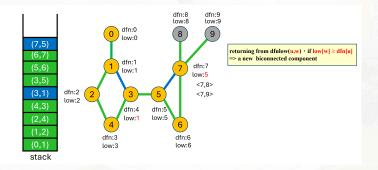
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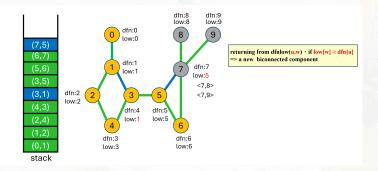
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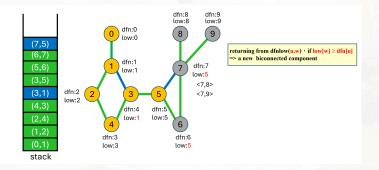
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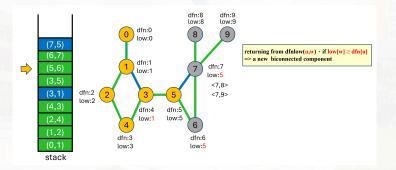
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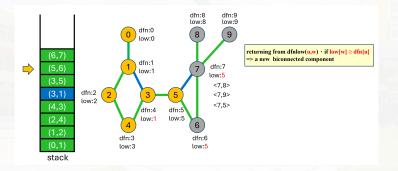
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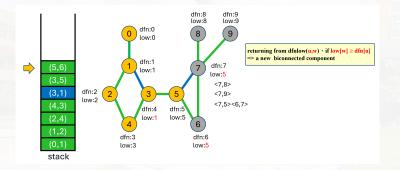
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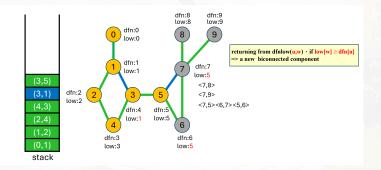
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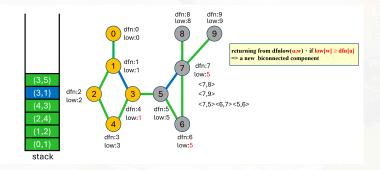
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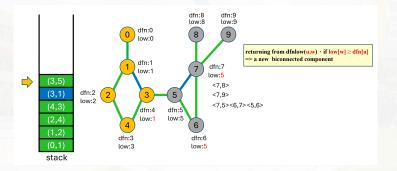
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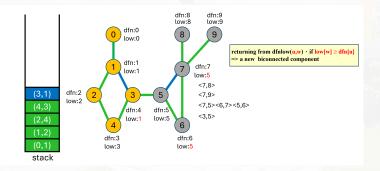
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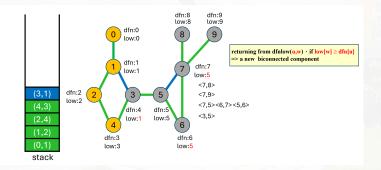
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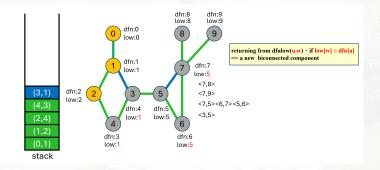
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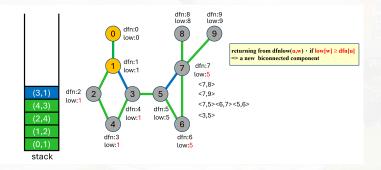
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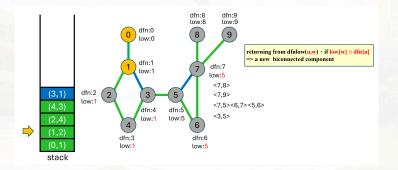
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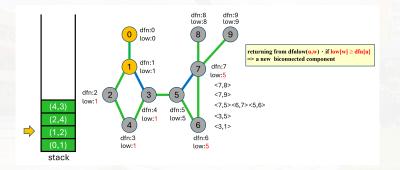
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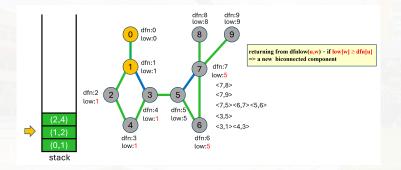
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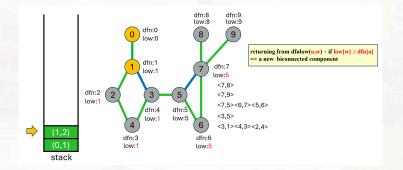
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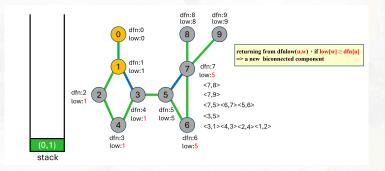
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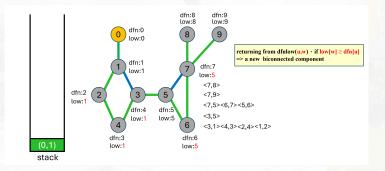
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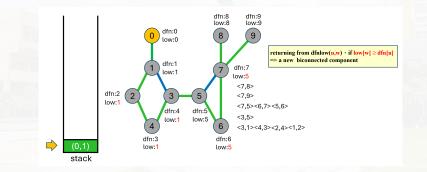
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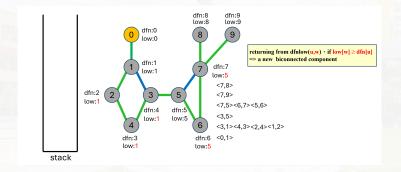
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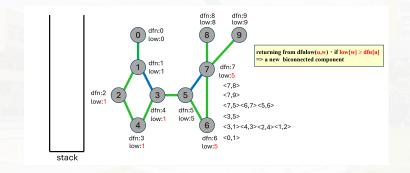
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Discussions



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