

# Depth-First Search and Breadth-First Search (DFS & BFS)

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# Outline

- 1 Introduction
- 2 Depth First Search (DFS)
- 3 Breadth-First Search (BFS)



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# Elementary Graph Operations

## Reachability

- **Given:** an undirected graph  $G = (V, E)$ , and a vertex  $v \in V(G)$
- **Goal:** visit all vertices in  $G$  that are reachable from  $v$ .



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## Reachability

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- **Goal:** visit all vertices in  $G$  that are reachable from  $v$ .
- The two ways of completing this task:
  - Depth-First Search (DFS)
    - Similar to the **preorder tree traversal**.
  - Breadth-First Search (BFS)
    - Similar to the **level-order tree traversal**.



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    - Similar to the **level-order tree traversal**.
- In the following discussion, we shall assume that the **linked adjacency list** representation for graphs is used.



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## Depth First Search (DFS) (1/2)

- We begin the search by visiting the start vertex,  $v$ .
- Next, we select an **unvisited** vertex,  $w$ , from  $v$ 's adjacency lists and carry out a DFS on  $w$ .
- We preserve our current position in  $v$ 's adjacency list by **placing it on a stack**.
- Eventually our search reaches a vertex, say  $u$ , that has no unvisited vertices on its adjacency list.





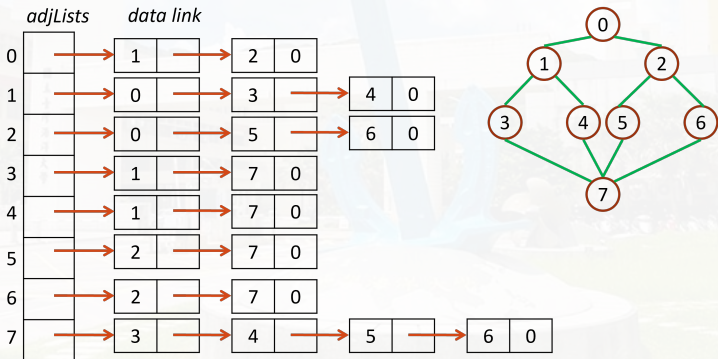
## Depth First Search (DFS) (2/2)

- At this point, we remove a vertex from **stack** and continue processing its adjacency list.
- Previously visited vertices are **discarded**; unvisited vertices are visited and placed on the stack.
- The search terminates when the stack is empty.



# DFS Example

- Using a stack and recursion.
  - It resembles the preorder tree traversal.



- The DFS order:  $v_0 \rightarrow v_1 \rightarrow v_3 \rightarrow v_7 \rightarrow v_4 \rightarrow v_5 \rightarrow v_2 \rightarrow v_6$ .



# The Pseudocode of DFS

```
DFS(G, u) {  
    u.visited = True  
    for each v in G.Adj[u]  
        if v.visited == False  
            DFS(G, v)  
}  
  
driving main () {  
    for each u in G  
        u.visited = false  
    for each u in G  
        DFS(G, u)  
}
```



## DFS in C

```
#define FALSE 0
#define TRUE 1
short int visited[MAX_VERTICES];
/* intializing to be FALSE for all */

void DFS(int v) {
/* DFS beginning at vertex v */
    nodePointer w;
    visited[v] = true;
    printf("%5d",v);
    for(w = graph[v]; w; w = w->link)
        if (!visited[w->vertex])
            DFS(w->vertex);
}
```



# Analysis of DFS

- For  $G = (V, E)$  represented by an **adjacency list**, vertices adjacent to  $v$  can be determined in  $|N(v)|$ , where  $N(v)$  denotes the set of vertices adjacent to  $v$  in  $G$ .



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  - Follow the chain of links,  $O(1)$  for deriving each neighbor of  $v$ .
- DFS examines each node in the adjacency lists at most **once**, the time cost for the search is  $O(e)$ , where  $e = |E|$ .



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- For  $G = (V, E)$  represented by an **adjacency matrix**, vertices adjacent to  $v$  can be determined in  $O(n)$  time, where  $n = |V|$ .
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- For  $G = (V, E)$  represented by an **adjacency list**, vertices adjacent to  $v$  can be determined in  $|N(v)|$ , where  $N(v)$  denotes the set of vertices adjacent to  $v$  in  $G$ .
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- For  $G = (V, E)$  represented by an **adjacency matrix**, vertices adjacent to  $v$  can be determined in  $O(n)$  time, where  $n = |V|$ .
    - One needs to scan the corresponding row of the adjacency matrix.
  - Total time:  $O(n^2)$ .





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## Breadth First Search (BFS) (1/2)

- The algorithm starts at vertex  $v$  and marks it as visited.
- Then visiting each of the vertices on  $v$ 's adjacency list.
- When we have visited all the vertices on  $v$ 's adjacency list, we visit all the unvisited vertices that are adjacent to the first vertex on  $v$ 's adjacency list.
- To implement this scheme, as we visit each vertex we place the vertex in a **queue**.



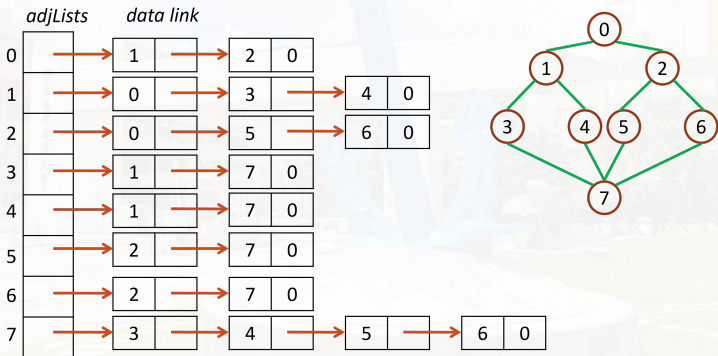
## Breadth-First Search (BFS) (2/2)

- When we have exhausted an adjacency list, we remove a vertex from the queue and proceed by examining each of the vertices on its adjacency list.
- Unvisited vertices are visited and placed on the queue; visited are ignored.
- Finish the search when the queue is empty.



# BFS Example

- Using a queue.
  - It resembles the level-order tree traversal.



- The DFS order:  $v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow v_3 \rightarrow v_4 \rightarrow v_5 \rightarrow v_6 \rightarrow v_7$ .



# The Pseudocode of BFS

```
BFS(G, u) { // let Q be the queue
    Q.enqueue(u)
    u.visited = True
    while (Q.empty() == False) { // when Q is not empty
        v = dequeue(Q)
        for all w in N(v) {
            if (w.visited == False) {
                Q.enqueue(w)
                w.visited = True
            }
        }
    }
}

driving main () {
    for each u in G
        u.visited = false
        BFS(G, u)
}
```



## BFS in C

```
void bfs(int v) {
    nodePointer w;
    front = rear = NULL; /* initialize queue */
    printf("%5d",v);
    visited[v] = TRUE;
    addq(v);

    while (front) {
        v = dequeue();
        for (w = graph[v]; w ; w->link)
            if (!visited[w->vertex]) {
                printf("%5d", w->vertex);
                enqueue(w->vertex);
                visited[w->vertex] = TRUE;
            }
    }
}
```



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- Since each vertex is placed on the queue **exactly once**, the while loop is iterated at most  $n$  times.



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  - For the **adjacency list** representation, this loop has a total cost of  $d_0 + d_1 + \dots + d_{n-1} = O(e)$ , where  $d_i = \text{degree}(v_i)$ .
- For the **adjacency matrix** representation, the while loop takes  $O(n)$  time for each vertex visited.
  - Therefore, the total time is  $O(n^2)$ .

As was true of DFS, all vertices visited, together with all edges incident to them, form a **connected component** of  $G$ .



# Discussions

