

Elementary Matrices

We have learned elementary row operations ...

\Rightarrow Say e_1, e_2, \dots

$$A \xrightarrow{e_1} A_1 \xrightarrow{e_2} A_2 \xrightarrow{e_3} \dots \xrightarrow{e_k} B$$
$$A \xleftarrow{e_1} A_1 \xleftarrow{e_2} A_2 \xleftarrow{e_3} \dots \xleftarrow{e_k} B$$

We say matrices A and B are **row equivalent**

if each of them can be obtained from the other by a sequence of elementary row operations.

Definition

A matrix E is called an elementary matrix if it can be obtained from an identity matrix by performing a single elementary row operation.

e.g. $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\times 3}$

$$\Rightarrow E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \times 3$$

$$\Rightarrow E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}$$

Example: Using elementary matrices = elementary row operations

Consider $A = \begin{bmatrix} 1 & 0 & 2 & 3 \\ 2 & -1 & 3 & 6 \\ 1 & 4 & 4 & 0 \end{bmatrix}$ and consider $E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}$

$$EA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 2 & 3 \\ 2 & -1 & 3 & 6 \\ 1 & 4 & 4 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 2 & 3 \\ 2 & -1 & 3 & 6 \\ 4 & 4 & 10 & 9 \end{bmatrix}$$

equivalent to $\begin{bmatrix} 1 & 0 & 2 & 3 \\ 2 & -1 & 3 & 6 \\ 1 & 4 & 4 & 0 \end{bmatrix} \times 3$

$$I = \begin{bmatrix} \text{row } i \\ \vdots \\ \text{row } i \\ \vdots \\ \text{row } i \end{bmatrix} \xrightarrow{\times c} E = \begin{bmatrix} \text{row } i \\ \vdots \\ \text{row } i \\ \vdots \\ \text{row } i \end{bmatrix} \xrightarrow{\times \frac{1}{c}}$$

$R_i^{(c)}$

$$I = \begin{bmatrix} \text{row } i \\ \vdots \\ \text{row } j \\ \vdots \\ \text{row } i \end{bmatrix} \xrightarrow{\text{interchange}} E = \begin{bmatrix} \text{row } i \\ \vdots \\ \text{row } j \\ \vdots \\ \text{row } i \end{bmatrix} \xrightarrow{\text{interchange}}$$

R_{ij}

$$I = \begin{bmatrix} \text{row } i \\ \vdots \\ \text{row } j \\ \vdots \\ \text{row } j \end{bmatrix} \xrightarrow{\times c} E = \begin{bmatrix} \text{row } i \\ \vdots \\ \text{row } j \\ \vdots \\ \text{row } j \end{bmatrix} \xrightarrow{\times (-c)}$$

$R_{ij}^{(c)}$

Example

$$\begin{bmatrix} 1 & 0 \\ 0 & 7 \end{bmatrix} \xrightarrow{\times 7} \begin{bmatrix} 1 & 0 \\ 0 & 7 \end{bmatrix} \xrightarrow{\times \frac{1}{7}} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Theorem: Every elementary matrix is invertible.

The inverse is also an elementary matrix.

$$E^{-1} \cdot E = I, \quad E \cdot E^{-1} = I$$

Theorem If $A \in F^{n \times n}$, then the following statements are equivalent:

- A is invertible
- $Ax = 0$ has only the trivial solution.
- The reduced row echelon form of A is I_n
- A is expressible as a product of elementary matrices.

(a) \Rightarrow (b)

Assume that A is invertible and let x_0 be any solution of $Ax = 0$

$$\Rightarrow (A^{-1}A)x_0 = A^{-1}0$$

$$\Rightarrow I \cdot x_0 = 0$$

$$\Rightarrow x_0 = 0 \Rightarrow Ax = 0 \text{ has only the trivial solution.}$$

(b) \Rightarrow (c):

The matrix form of the system $Ax = 0$:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = 0$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = 0$$

Assume that it has only the trivial solution

By Gauss-Jordan elimination, the reduced row echelon form:

$$\begin{bmatrix} 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & 1 \end{bmatrix} \Leftrightarrow \begin{cases} x_1 = 0 \\ x_2 = 0 \\ \vdots \\ x_n = 0 \end{cases}$$

\therefore The reduced row echelon form is I_n

(c) \Rightarrow (d): Assume that the reduced row echelon form is I_n

\therefore We can find elementary matrices E_1, E_2, \dots, E_k such that

$$\underline{E_k E_{k-1} \dots E_2 E_1 A} = I_n \quad \text{the same}$$

Since elementary matrices are invertible,

$$\therefore (E_1^{-1} \cdot E_2^{-1} \dots E_k^{-1}) (E_k E_{k-1} \dots E_2 E_1 A) = E_1^{-1} E_2^{-1} \dots E_k^{-1} I_n$$

$$\Rightarrow A = E_1^{-1} E_2^{-1} \dots E_k^{-1} I_n \quad \therefore \underline{E_k \dots E_3 E_2 E_1} A = I$$

$$(d) \Rightarrow (a): \quad A = I E_1^{-1} E_2^{-1} \dots E_k^{-1} \quad \therefore \underline{A E_k E_{k-1} \dots E_2 E_1} = I$$

If A is a product of elementary matrices,

then A is a product of invertible matrices

$\Rightarrow A$ is invertible \star

Therefore, we are aware of a method of finding an inverse of a matrix!

$$A^{-1} = E_k E_{k-1} \dots E_2 E_1 I_n$$

\Rightarrow Here comes the Inversion Algorithm:

Example: $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{bmatrix}$

We adjoin the identity matrix I_3 to the right side of A : $[A | I]$

The goal:

$$[A | I] \rightsquigarrow [I | A^{-1}]$$

$$\left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 2 & 5 & 3 & 0 & 1 & 0 \\ 1 & 0 & 8 & 0 & 0 & 1 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & -2 & 5 & -1 & 0 & 1 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 9 & 5 & -2 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & -1 & -5 & 2 & 1 \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 9 & 5 & -2 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & 1 & -5 & 2 & -1 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -40 & 16 & 9 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & -5 & 2 & -1 \end{array} \right]$$

$$\therefore A^{-1} = \begin{bmatrix} -40 & 16 & 9 \\ 13 & -5 & -3 \\ 5 & -2 & -1 \end{bmatrix} \star$$

Example $A = \begin{bmatrix} 1 & 6 & 4 \\ 2 & 4 & -1 \\ -1 & 2 & 5 \end{bmatrix}$

$$\left[\begin{array}{ccc|ccc} 1 & 6 & 4 & 1 & 0 & 0 \\ 2 & 4 & -1 & 0 & 1 & 0 \\ -1 & 2 & 5 & 0 & 0 & 1 \end{array} \right] \begin{array}{l} \times (-2) \\ \\ \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} 1 & 6 & 4 & 1 & 0 & 0 \\ 0 & -8 & -9 & -2 & 1 & 0 \\ 0 & 8 & 9 & 1 & 0 & 1 \end{array} \right] \times (1)$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} 1 & 6 & 4 & 1 & 0 & 0 \\ 0 & -8 & -9 & -2 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 & 1 \end{array} \right]$$

→ the reduced row echelon form is NOT I_3 !!

A is NOT invertible *

Example Find the inverse of the product

$$A = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -c & 1 \end{bmatrix}}_{W_1} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -b & 0 & 1 \end{bmatrix}}_{W_2} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ -a & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{W_3} \quad (91 \text{ \del{p} } 51E)$$

(sol):

We observe that W_1, W_2, W_3 are elementary matrices

∴ W_1, W_2, W_3 are invertible

$$\text{i.e., } A = R_{23}^{(-c)} R_{13}^{(b)} R_{12}^{(a)}$$

$$\therefore A^{-1} = (R_{23}^{(-c)} R_{13}^{(b)} R_{12}^{(a)})^{-1}$$

$$= (R_{12}^{(a)})^{-1} (R_{13}^{(b)})^{-1} (R_{23}^{(-c)})^{-1}$$

$$= R_{12}^{(a)} R_{13}^{(b)} R_{23}^{(c)}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ a & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ b & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & c & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ a & 1 & 0 \\ b & c & 1 \end{bmatrix} \#$$

Example Let $A = \begin{bmatrix} 1 & 0 \\ -5 & 2 \end{bmatrix}$. Find elementary matrices E_1 and E_2 such that $A = E_1 E_2$ (98 KUCISE)

(sol):

$$A = \begin{bmatrix} 1 & 0 \\ -5 & 2 \end{bmatrix}$$

$$R_{12}^{(5)} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

$$R_2^{(\frac{1}{2})} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$\therefore R_2^{(\frac{1}{2})} R_{12}^{(5)} A = I$$

$$\Rightarrow A = (R_2^{(\frac{1}{2})} R_{12}^{(5)})^{-1}$$

$$= R_{12}^{(-5)} R_2^{(2)}$$

$$= \begin{bmatrix} 1 & 0 \\ -5 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\therefore E_1 = \begin{bmatrix} 1 & 0 \\ -5 & 1 \end{bmatrix}, E_2 = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

$$B = R_2^{(\frac{1}{2})} R_{12}^{(5)} R_{34}(A)$$

$$\therefore (R_2^{(\frac{1}{2})} R_{12}^{(5)})^{-1} B = A$$

$$R_{34} R_{12}^{(-5)} R_2^{(2)}$$

$$x_1 = 1, x_2 = -1, x_3 = 2$$

Theorem A system of linear equations has zero, one, or infinitely many solutions. There are NO other possibilities.

(proof):

If $A\mathbf{x} = \mathbf{b}$ is a system of linear equations. Then exactly one of the following is true:

- (a) the system has no solutions
- (b) the system has exactly one solution
- ✓ (c) the system has > 1 solution

Let $\mathbf{x}_1, \mathbf{x}_2$ be any two distinct solutions of $A\mathbf{x} = \mathbf{b}$

$$\mathbf{x}_0 = \mathbf{x}_1 - \mathbf{x}_2 \neq \mathbf{0}$$

$$\therefore A\mathbf{x}_0 = A(\mathbf{x}_1 - \mathbf{x}_2) = A\mathbf{x}_1 - A\mathbf{x}_2 = \mathbf{b} - \mathbf{b} = \mathbf{0}$$

if we let $k \in \mathbb{F}$ be any scalar, then

$$\begin{aligned} A(\mathbf{x}_1 + k\mathbf{x}_0) &= A\mathbf{x}_1 + A(k\mathbf{x}_0) = A\mathbf{x}_1 + k(A\mathbf{x}_0) \\ &= \mathbf{b} + k \cdot \mathbf{0} = \mathbf{b} + \mathbf{0} = \mathbf{b} \end{aligned}$$

So $\mathbf{x}_1 + k\mathbf{x}_0$ is a solution of $A\mathbf{x} = \mathbf{b}$.

Since $\mathbf{x}_0 \neq \mathbf{0}$, there are infinitely many choices for k .

$\therefore A\mathbf{x} = \mathbf{b}$ has infinitely many solutions.

Theorem If $A \in \mathbb{F}^{n \times n}$, A is invertible, then
 for each $b \in \mathbb{F}^{n \times 1}$, $Ax = b$ has exactly one solution
 $x = A^{-1}b$

(proof):

$$\therefore A(A^{-1}b) = b$$

$\therefore x = A^{-1}b$ is a solution of $Ax = b$

Assume that x_0 is an arbitrary solution of $Ax = b$

$$\Rightarrow Ax_0 = b$$

$$\Rightarrow A^{-1}(Ax_0) = A^{-1}b$$

$$\Rightarrow x_0 = A^{-1}b = x$$

Example

$$x_1 + 2x_2 + 3x_3 = 5$$

$$2x_1 + 5x_2 + 3x_3 = 3$$

$$x_1 + 8x_3 = 17$$

$$\Rightarrow A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{bmatrix}, \quad b = \begin{bmatrix} 5 \\ 3 \\ 17 \end{bmatrix}, \quad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\text{Find } A^{-1} \Rightarrow A^{-1} = \begin{bmatrix} -40 & 16 & 9 \\ 13 & -5 & -3 \\ 5 & -2 & -1 \end{bmatrix}$$

$$\therefore x = A^{-1}b = \begin{bmatrix} -40 & 16 & 9 \\ 13 & -5 & -3 \\ 5 & -2 & -1 \end{bmatrix} \begin{bmatrix} 5 \\ 3 \\ 17 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$

$$\therefore x_1 = 1, x_2 = -1, x_3 = 2$$

Linear Systems with a Common Coefficient Matrix

Example:

$$A\bar{x} = b_1, A\bar{x} = b_2, A\bar{x} = b_3, \dots, A\bar{x} = b_k$$

$$\Rightarrow \bar{x}_1 = A^{-1}b_1, \bar{x}_2 = A^{-1}b_2, \dots, \bar{x}_k = A^{-1}b_k$$

An efficient way of expression:

$$[A \mid b_1 \mid b_2 \mid \dots \mid b_k]$$

Example

$$\begin{aligned} \text{(a)} \quad & x_1 + 2x_2 + 3x_3 = 4 \\ & 2x_1 + 5x_2 + 3x_3 = 5 \\ & x_1 + 8x_3 = 9 \end{aligned}$$

$$\begin{aligned} \text{(b)} \quad & x_1 + 2x_2 + 3x_3 = 1 \\ & 2x_1 + 5x_2 + 3x_3 = 6 \\ & x_1 + 8x_3 = -6 \end{aligned}$$

(sol):

$$\begin{array}{c} (-2) \\ r_{12} \end{array} \Rightarrow \left[\begin{array}{ccc|cc} 1 & 2 & 3 & 4 & 1 \\ 2 & 5 & 3 & 5 & 6 \\ 1 & 0 & 8 & 9 & -6 \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|cc} 1 & 2 & 3 & 4 & 1 \\ 0 & 1 & -3 & -3 & 4 \\ 1 & 0 & 8 & 9 & -6 \end{array} \right]$$

$$\begin{array}{c} (-1) \\ r_{13} \end{array} \Rightarrow \left[\begin{array}{ccc|cc} 1 & 2 & 3 & 4 & 1 \\ 0 & 1 & -3 & -3 & 4 \\ 0 & -2 & 5 & 5 & -7 \end{array} \right]$$

$$\begin{array}{c} (-2) \\ r_{21}, r_{23} \end{array} \Rightarrow \left[\begin{array}{ccc|cc} 1 & 0 & 9 & 10 & -7 \\ 0 & 1 & -3 & -3 & 4 \\ 0 & 0 & -1 & -1 & 1 \end{array} \right]$$

$$\begin{array}{c} (3) \\ r_{32}, r_{31} \end{array} \Rightarrow \left[\begin{array}{ccc|cc} 1 & 0 & 0 & 1 & 2 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & -1 \end{array} \right]$$

$$\begin{array}{c} (-1) \\ r_3 \end{array} \Rightarrow \left[\begin{array}{ccc|cc} 1 & 0 & 9 & 10 & -7 \\ 0 & 1 & -3 & -3 & 4 \\ 0 & 0 & 1 & 1 & -1 \end{array} \right]$$

\therefore (a): $x_1 = 1, x_2 = 0, x_3 = 1$

(b): $x_1 = 2, x_2 = 1, x_3 = 1$

Equivalence Theorem

If $A \in \mathbb{F}^{n \times n}$ and ~~A is invertible~~, then the following are equivalent

- (a) A is invertible
- (b) $A\mathbf{x} = \mathbf{0}$ has only the trivial solution
- (c) The reduced row echelon form of $A = I_n$
- (d) A is expressible as a product of elementary matrices
- (e) $A\mathbf{x} = \mathbf{b}$ is consistent for every $n \times 1$ matrix \mathbf{b} NEW!
- (f) $A\mathbf{x} = \mathbf{b}$ has exactly one solution for every $n \times 1$ matrix \mathbf{b} .

Try (e) \Rightarrow (a): $A\mathbf{x} = \mathbf{b}$ is consistent for every $n \times 1$ matrix \mathbf{b} .

$$\text{So, } A\mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, A\mathbf{x} = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, A\mathbf{x} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

Let $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$ be solutions of the above systems.

$$\text{Let } C \in \mathbb{F}^{n \times n} \text{ be } C = [\mathbf{x}_1 \mid \mathbf{x}_2 \mid \mathbf{x}_3 \mid \dots \mid \mathbf{x}_n]$$

$$\therefore \underbrace{A}_{\text{square}} \underbrace{C}_{\text{square}} = [A\mathbf{x}_1 \mid A\mathbf{x}_2 \mid \dots \mid A\mathbf{x}_n] = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix} = I$$

$$\Rightarrow C = A^{-1}, \text{ thus } A \text{ is invertible} \neq$$

Note:

Theorem 1.6.3 Let A be a square matrix.

- (a) If B is a square matrix satisfying $BA = I$, then $B = A^{-1}$
- (b) If B is a square matrix satisfying $AB = I$, then $B = A^{-1}$

(proof) (a): Goal: show that A is invertible \Rightarrow it suffices to show that

$$A\mathbf{x} = \mathbf{0} \text{ has only the trivial solution}$$

let \mathbf{x}_0 be any solution of the system $\therefore A\mathbf{x}_0 = \mathbf{0} \Rightarrow B(A\mathbf{x}_0) = B\mathbf{0} = \mathbf{0}$
 $\Rightarrow I\mathbf{x}_0 = \mathbf{0} \Rightarrow \mathbf{x}_0 = \mathbf{0}$

OK! Now we know A is invertible

$$\text{Hence, } BA = I \Rightarrow BAA^{-1} = IA^{-1} \Rightarrow BI = IA^{-1} \Rightarrow B = A^{-1}$$

(b) Goal: show that B is invertible, so that $AB = I \Rightarrow ABB^{-1} = B^{-1} \Rightarrow A = B^{-1}$
 $\therefore A^{-1} = (B^{-1})^{-1} = B$

We can determine consistency of the system of equations by elimination! Especially when $A \in \mathbb{F}^{n \times n}$ is NOT invertible!

Example:

What conditions must b_1 , b_2 , and b_3 satisfy in order for the system of equations:

$$x_1 + x_2 + 2x_3 = b_1$$

$$x_1 + x_3 = b_2$$

$$2x_1 + x_2 + 3x_3 = b_3$$

to be consistent?

sol):

The augmented matrix is

$$\left[\begin{array}{ccc|c} 1 & 1 & 2 & b_1 \\ 1 & 0 & 1 & b_2 \\ 2 & 1 & 3 & b_3 \end{array} \right] \begin{array}{l} \leftarrow x_1^{(-1)} \\ \leftarrow r_2^{(-1)} \\ \leftarrow x_3^{(-2)} \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 2 & b_1 \\ 0 & -1 & -1 & b_2 - b_1 \\ 0 & -1 & -1 & b_3 - 2b_1 \end{array} \right] \rightarrow x_2^{(-1)} r_2^{(-1)}$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 2 & b_1 \\ 0 & 1 & 1 & b_1 - b_2 \\ 0 & -1 & -1 & b_3 - 2b_1 \end{array} \right] \begin{array}{l} \leftarrow x_1^{(1)} \\ \leftarrow r_2^{(1)} \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 2 & b_1 \\ 0 & 1 & 1 & b_1 - b_2 \\ 0 & 0 & 0 & b_3 - b_2 - b_1 \end{array} \right]$$

\therefore The system has a solution iff $b_3 - b_2 - b_1 = 0$

$$\therefore b = \begin{bmatrix} b_1 \\ b_2 \\ b_1 + b_2 \end{bmatrix}, \text{ for } b_1, b_2 \in \mathbb{F}$$

$$\Downarrow \\ b_3 = b_1 + b_2$$

Example

What conditions must b_1 , b_2 , and b_3 satisfy in order for the system of equations:

$$x_1 + 2x_2 + 3x_3 = b_1$$

$$2x_1 + 5x_2 + 3x_3 = b_2$$

$$x_1 + 8x_3 = b_3$$

to be consistent?

(sol): The augmented matrix is:

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & b_1 \\ -2 & 5 & 3 & b_2 \\ 1 & 0 & 8 & b_3 \end{array} \right] \begin{array}{l} \leftarrow R_{12}^{(-2)} \\ \leftarrow R_{13}^{(-1)} \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & b_1 \\ 0 & 1 & -3 & b_2 - 2b_1 \\ 0 & -2 & 5 & b_3 - b_1 \end{array} \right] \begin{array}{l} \leftarrow R_{21}^{(-2)} \\ \leftarrow R_{23}^{(2)} \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 9 & 5b_1 - 2b_2 \\ 0 & 1 & -3 & b_2 - 2b_1 \\ 0 & 0 & -1 & b_3 + 2b_2 - 5b_1 \end{array} \right] \begin{array}{l} \leftarrow R_{31}^{(9)} \\ \leftarrow R_{32}^{(-9)} \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 9 & 5b_1 - 2b_2 \\ 0 & 1 & -3 & b_2 - 2b_1 \\ 0 & 0 & 1 & 5b_1 - 2b_2 - b_3 \end{array} \right] \begin{array}{l} \leftarrow R_{31}^{(-9)} \\ \leftarrow R_{32}^{(3)} \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & -40b_1 + 16b_2 + 9b_3 \\ 0 & 1 & 0 & 13b_1 - 5b_2 - 3b_3 \\ 0 & 0 & 1 & 5b_1 - 2b_2 - b_3 \end{array} \right]$$

There are no restrictions on b_1 , b_2 , and b_3

$$\therefore x_1 = -40b_1 + 16b_2 + 9b_3$$

$$\begin{cases} x_2 = 13b_1 - 5b_2 - 3b_3 \\ x_3 = 5b_1 - 2b_2 - b_3 \end{cases} \text{ for } b_1, b_2, b_3 \in \mathbb{F}$$