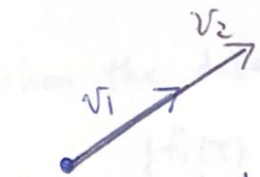
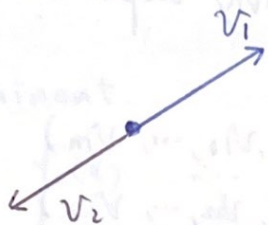


Remark on § linear independency

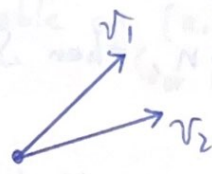
in \mathbb{R}^2 or \mathbb{R}^3



linearly dependent



linearly dependent



linearly independent

Definition

$S = \{v_1, v_2, \dots, v_r\}$ is linearly independent :

if no vector in S can be expressed as a linear combination of the others.

Theorem A nonempty set $S = \{v_1, v_2, \dots, v_r\}$ in a vector

space V is linearly independent if and only if

the coefficients satisfying

$$k_1 v_1 + k_2 v_2 + \dots + k_r v_r = \mathbf{0}$$

are $k_1 = k_2 = \dots = k_r = 0$

Theorem

(a) A set with finitely many vectors that contains $\mathbf{0}$ is linearly dependent.

(b) A set with exactly two vectors is linearly independent if and only if neither vector is a scalar multiple of the other.

4.4.3
Theorem Let $S = \{v_1, v_2, \dots, v_r\}$ be a set of vectors in \mathbb{R}^n .
If $r > n$, then S is linearly dependent.

(proof):

Suppose that $v_1 = (v_{11}, v_{12}, \dots, v_{1n})$
 $v_2 = (v_{21}, v_{22}, \dots, v_{2n})$
 \vdots
 $v_r = (v_{r1}, v_{r2}, \dots, v_{rn})$

Consider $k_1 v_1 + k_2 v_2 + \dots + k_r v_r = 0$

$$\Rightarrow \begin{cases} v_{11} k_1 + v_{21} k_2 + \dots + v_{r1} k_r = 0 \\ v_{12} k_1 + v_{22} k_2 + \dots + v_{r2} k_r = 0 \\ \vdots \\ v_{1n} k_1 + v_{2n} k_2 + \dots + v_{rn} k_r = 0 \end{cases}$$

it's a homogeneous system of n equations and
 r unknowns, $r > n$

\Rightarrow the system has nontrivial solutions

$\therefore S$ is linearly dependent \ast

We also have linear dependence of "functions".

Example: $f_1 = \sin^2 x$, $f_2 = \cos^2 x$, $f_3 = 5$

$$\begin{aligned} \because 5f_1 + 5f_2 - f_3 &= 5\sin^2 x + 5\cos^2 x - 5 \\ &= 5(\sin^2 x + \cos^2 x) - 5 = 0 \end{aligned}$$

$\therefore \{f_1, f_2, f_3\}$ is linearly dependent.

★ (Wronskian) If $f_1 = f_1(x), f_2 = f_2(x), \dots, f_n = f_n(x)$ are functions that are $n-1$ times differentiable on $[a, b]$, where $f_1, f_2, \dots, f_n : [a, b] \rightarrow \mathbb{R}$ (or $(-\infty, \infty)$) then the determinant

$$W(x) = \begin{vmatrix} f_1(x) & f_2(x) & \dots & f_n(x) \\ f_1'(x) & f_2'(x) & \dots & f_n'(x) \\ \vdots & \vdots & \ddots & \vdots \\ f_1^{(n-1)}(x) & f_2^{(n-1)}(x) & \dots & f_n^{(n-1)}(x) \end{vmatrix}$$

is called the Wronskian of f_1, f_2, \dots, f_n .

Let's go deeper!

Suppose that f_1, f_2, \dots, f_n are linearly dependent.

Then $k_1 f_1 + k_2 f_2 + \dots + k_n f_n = 0$ is satisfied by not-all-zero coefficients k_1, k_2, \dots, k_n .

$k_1 f_1(x) + k_2 f_2(x) + \dots + k_n f_n(x) = 0$ is satisfied for all x .

(taking differentiations

$$k_1 f_1(x) + k_2 f_2(x) + \dots + k_n f_n(x) = 0$$

$$k_1 f_1'(x) + k_2 f_2'(x) + \dots + k_n f_n'(x) = 0$$

$$\vdots$$

$$k_1 f_1^{(n-1)}(x) + k_2 f_2^{(n-1)}(x) + \dots + k_n f_n^{(n-1)}(x) = 0$$

$$\Rightarrow \begin{bmatrix} f_1(x) & f_2(x) & \dots & f_n(x) \\ f_1'(x) & f_2'(x) & \dots & f_n'(x) \\ \vdots & \vdots & \ddots & \vdots \\ f_1^{(n-1)}(x) & f_2^{(n-1)}(x) & \dots & f_n^{(n-1)}(x) \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

has a nontrivial solution for all x

$$\Rightarrow W(x) = 0 \text{ for all } x$$

n 個未知數

$n-1$ 個方程

Example. Use the Wronskian to show that $f_1 = x$, $f_2 = \sin x$ are linearly independent vectors in $C^\infty(-\infty, \infty)$
↳ infinitely differentiable on $(-\infty, \infty)$

(sol):

The Wronskian is

$$W(x) = \begin{vmatrix} x & \sin x \\ 1 & \cos x \end{vmatrix} = x \cos x - \sin x$$

$$\therefore W\left(\frac{\pi}{2}\right) = \frac{\pi}{2} \cos\left(\frac{\pi}{2}\right) - \sin\left(\frac{\pi}{2}\right) = -1 \neq 0$$

∴ f_1, f_2 are linearly independent *

Example Prove that $\{\sin x, \cos x, x \sin x\}$ is linearly independent. (證大資291)

(proof):

The Wronskian is

$$W(x) = \begin{vmatrix} \sin x & \cos x & x \sin x \\ \cos x & -\sin x & \sin x + x \cos x \\ -\sin x & -\cos x & 2 \cos x - x \sin x \end{vmatrix}$$

Take $x = 0$,

$$W(0) = \begin{vmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & -1 & 2 \end{vmatrix} = -2 \neq 0$$

∴ $\{\sin x, \cos x, x \sin x\}$ is linearly independent *

Remark on spanning set

Given $u_1 = (1, 2, 1)$, $u_2 = (-2, -4, -2)$, $u_3 = (0, 2, 3)$, $u_4 = (2, 0, -3)$, $u_5 = (-3, 8, 16)$, determine whether $u = (2, 6, 8)$ can be expressed as a linear combination of u_1, u_2, u_3, u_4, u_5 .

(sol):

$$\text{Let } A = \begin{bmatrix} 1 & 2 & 1 \\ -2 & -4 & -2 \\ 0 & 2 & 3 \\ 2 & 0 & -3 \\ -3 & 8 & 16 \\ \hline 2 & 6 & 8 \end{bmatrix}$$

$$\begin{array}{l} r_{12}, r_{14} \\ r_{15}, r_{16} \end{array}$$

$$B = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 2 & 3 \\ 0 & -4 & -5 \\ 0 & 14 & 19 \\ \hline 0 & 2 & 6 \end{bmatrix}$$

$$C = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & -2 \\ \hline 0 & 0 & 3 \end{bmatrix}$$

$$\begin{array}{l} r_{45}, r_{46} \end{array}$$

$$D = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 0 \end{bmatrix}$$

So we have

$$-3C_4 + C_6 = 0$$

$$\rightarrow C_4 = 2B_3 + B_4, \quad C_6 = -B_3 + B_6$$

$$\therefore -3(2B_3 + B_4) + (-B_3 + B_6) = 0$$

$$\Rightarrow -7B_3 - 3B_4 + B_6 = 0$$

$$\text{And, } B_3 = A_3, \quad B_4 = -2A_1 + A_4, \quad B_6 = -2A_1 + A_6$$

$$\therefore -7A_3 - 3(-2A_1 + A_4) + (-2A_1 + A_6) = 0$$

$$\Rightarrow 4A_1 + 0A_2 - 7A_3 - 3A_4 + 0A_5 + A_6 = 0$$

$$\Rightarrow 4u_1 + 0u_2 - 7u_3 - 3u_4 + 0u_5 + u = 0$$

$$\therefore u = -4u_1 + 0u_2 + 7u_3 + 3u_4 + 0u_5$$

Note: Never do row interchange!

Example: Determine whether the matrix $\begin{bmatrix} -1 & 7 \\ 8 & -1 \end{bmatrix}$ is a linear combination of $\begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$, $\begin{bmatrix} 2 & -3 \\ 0 & 2 \end{bmatrix}$, and $\begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix}$

(98 雲科大資工)

sol):

$$\begin{bmatrix} 1 & 0 & 2 & 1 \\ 2 & -3 & 0 & 2 \\ 0 & 1 & 2 & 0 \\ -1 & 7 & 8 & -1 \end{bmatrix} \xrightarrow[\substack{(-2) \cdot (1) \\ V_{12}, V_{14}}]{(1)} \begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & -3 & -4 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 7 & 10 & 0 \end{bmatrix}$$

$$\xrightarrow[\substack{(\frac{1}{3}) \\ V_{23}, V_{24}}]{(\frac{7}{3})} \begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & -3 & -4 & 0 \\ 0 & 0 & \frac{2}{3} & 0 \\ 0 & 0 & \frac{2}{3} & 0 \end{bmatrix} \xrightarrow[(-1)]{V_{34}} \begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & -3 & -4 & 0 \\ 0 & 0 & \frac{2}{3} & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

\therefore The answer is "yes"

Exercise ⁽³⁻³⁴⁾ Let $u = (3, 0, 2)$, $v = (0, 1, 1)$, and $w = (-3, 1, 0)$

Is $(0, 3, 5)$ in $\text{span}\{u, v, w\}$? (98 中正資工)

Exercise ³⁻³⁵ Let $v_1 = (1, -1, -2)$, $v_2 = (5, -4, -7)$, $v_3 = (-3, 1, 0)$, and $y = (-4, 3, h)$. Find the value of h such that y is in $\text{span}\{v_1, v_2, v_3\}$. (91 輔大資工)

Note: Never do row interchange!

How to determine if a set of vectors spans the vector space?

Example: Determine whether the vectors

$$v_1 = (1, 1, 2), v_2 = (1, 0, 1), \text{ and } v_3 = (2, 1, 3)$$

spans \mathbb{R}^3

(sol): Let $b = (b_1, b_2, b_3)$ be an arbitrary vector in \mathbb{R}^3

$$\text{Suppose that } b = k_1 v_1 + k_2 v_2 + k_3 v_3$$

$$\therefore (b_1, b_2, b_3) = (k_1 + k_2 + 2k_3, k_1 + k_3, 2k_1 + k_2 + 3k_3)$$

$$\Rightarrow k_1 + k_2 + 2k_3 = b_1$$

$$k_1 + k_3 = b_2$$

$$2k_1 + k_2 + 3k_3 = b_3$$

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 3 \end{bmatrix}$$

The system is consistent if and only if $\det(A) \neq 0$

But we have $\det(A) = 0 \rightarrow$ check by yourself.

$\therefore v_1, v_2, v_3$ do not span \mathbb{R}^3

Example: Determine whether $S = \{x+x^2, x-x^2, 1+x, 1-x\}$

spans \mathbb{P}_2 .

(sol): An arbitrary vector in \mathbb{P}_2 is of the form $a+bx+cx^2$

$$\therefore \text{Let } k_1(x+x^2) + k_2(x-x^2) + k_3(1+x) + k_4(1-x) = a+bx+cx^2$$

$$\Rightarrow k_3 + k_4 = a$$

$$k_1 + k_2 + k_3 - k_4 = b$$

$$k_1 - k_2 = c$$

$$A = \begin{bmatrix} 0 & 0 & 1 & 1 \\ 1 & 1 & 1 & -1 \\ 1 & -1 & 0 & 0 \end{bmatrix} \rightarrow \text{not square!}$$

Consider the augmented matrix

$$\begin{bmatrix} 0 & 0 & 1 & 1 & a \\ 1 & 1 & 1 & -1 & b \\ 1 & -1 & 0 & 0 & c \end{bmatrix}$$

\rightarrow reduced row echelon form:

$$\begin{bmatrix} 1 & 0 & 0 & 0 & \frac{-a+b+c}{2} \\ 0 & 1 & 0 & 0 & \frac{-a+b-c}{2} \\ 0 & 0 & 1 & -1 & a \end{bmatrix}$$

check by yourself.

\therefore the system is consistent

for every choice $a, b,$ and $c \Rightarrow \text{span}(S) = \mathbb{P}_2$